

THE 5-MASS KITE INTEGRAL FAMILY ON TWO TORI



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based on [2401.14307](#) with
Mathieu Giroux, Andrzej Pokraka and Yoann Sohnle

11.6.2024, Amplitudes 2024, Princeton



Funded by
the European Union

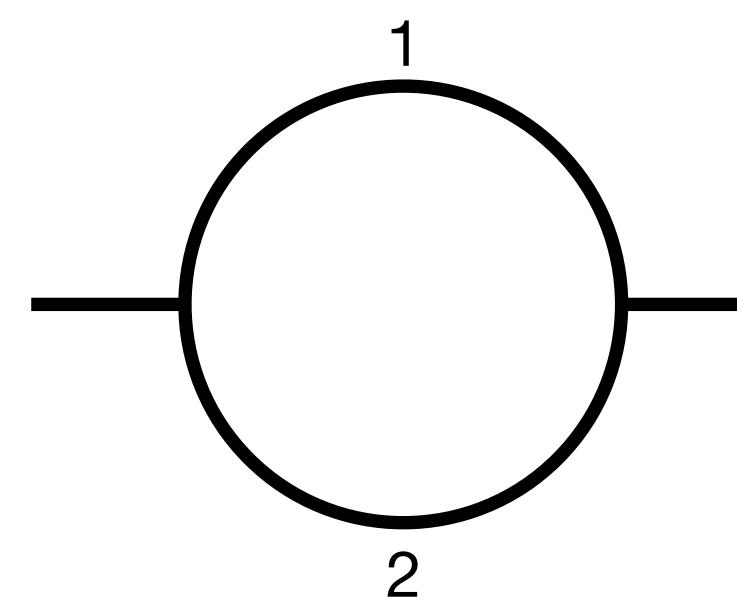


Bethe Center for
Theoretical Physics

MOTIVATION

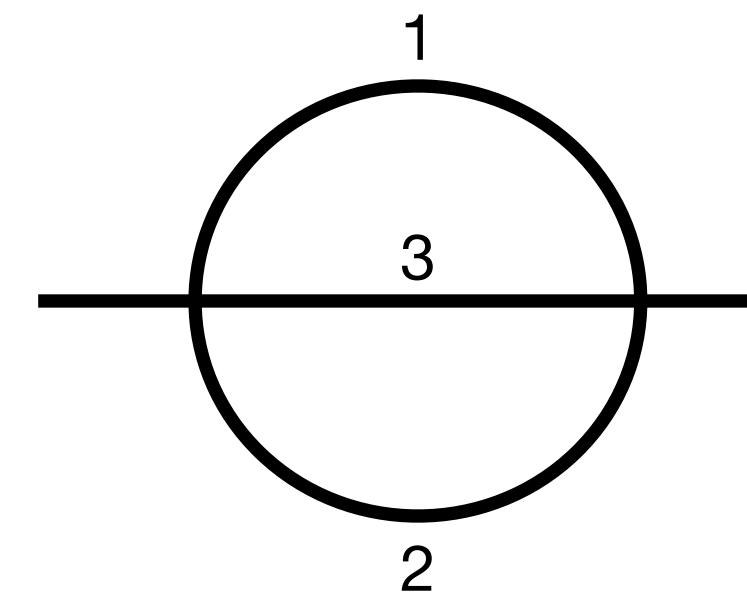
The kite integral family is the most general 2-loop 2-point Feynman integral family.

1 Loop: Bubble



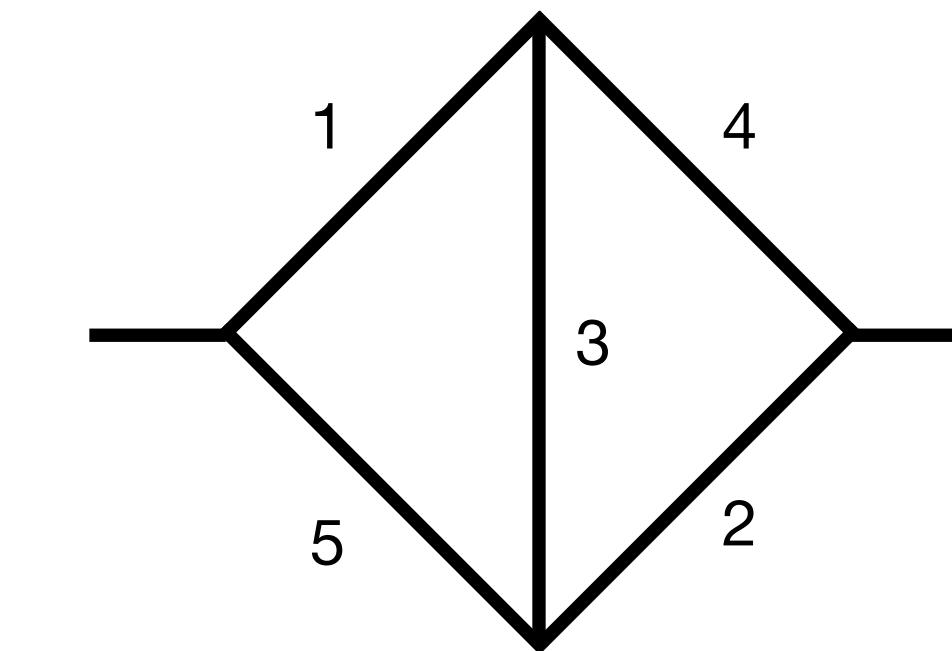
Sunrise: Solved

[Bogner, Müller-Stach, Weinzierl;19]



2 Loop: Kite

[Giroux, Pokraka, FP, Sohnle; 24]



elliptics

more elliptics

5 irreducible scalar products:
 $\{\ell_1^2, \ell_2^2, \ell_1 \cdot \ell_2, \ell_1 \cdot p, \ell_2 \cdot p\}$

5 propagators in
the most generic case

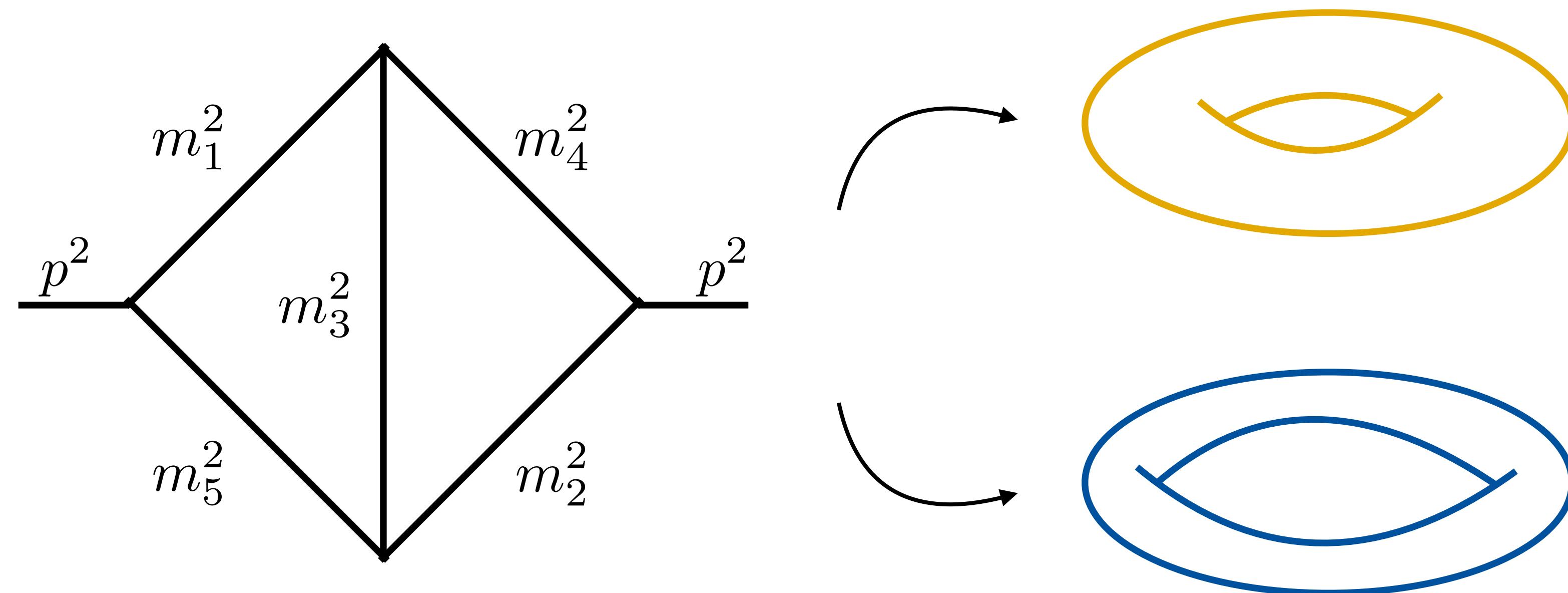
We analytically **solve all scalar 2-loop 2-point** Feynman integrals!

MOTIVATION

Tori & higher genus/dimensional geometries appear in multi-loop Feynman integrals. **Talk by Lorenzo**

But: Only few results with **multiple tori** or **many kinematic parameters on the torus** so far.

[Adams, Chaubey, Weinzierl;18 | Müller, Weinzierl;22 | Duhr, Klemm, Nega, Tancredi;22 | Görgen, Nega, Tancredi, Wagner; 23 ...]



Kite integral: Two tori & five kinematic parameters

THE KITE INTEGRAL FAMILY

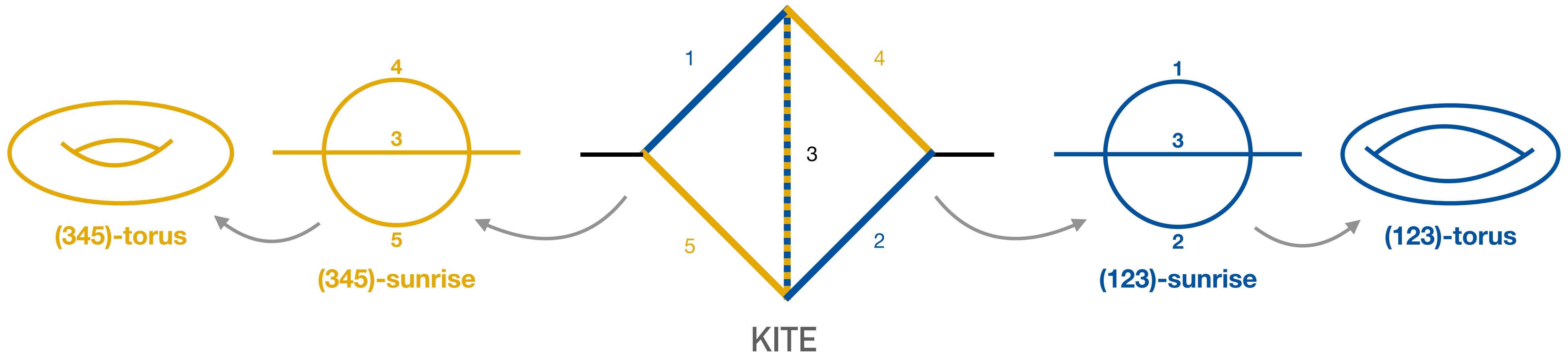
Goal: Solve the kite integral family analytically in $d = 2 - 2\varepsilon$.

$$I_\nu = \frac{e^{2\gamma_E \varepsilon} \mu^{2(|\nu|-d)}}{(i\pi)^d} \int \frac{d^d \ell_1 d^d \ell_2}{D_1^{\nu_1} D_2^{\nu_2} D_3^{\nu_3} D_4^{\nu_4} D_5^{\nu_5}}$$

$$\begin{aligned} D_1 &= -\ell_1^2 + \boxed{m_1^2} \\ D_4 &= -\ell_2^2 + \boxed{m_4^2} \end{aligned}$$

$$\begin{aligned} D_2 &= -(\ell_2 - p)^2 + \boxed{m_2^2} \\ D_5 &= -(\ell_1 - p)^2 + \boxed{m_5^2} \end{aligned}$$

$$D_3 = -(\ell_1 - \ell_2)^2 + \boxed{m_3^2}$$



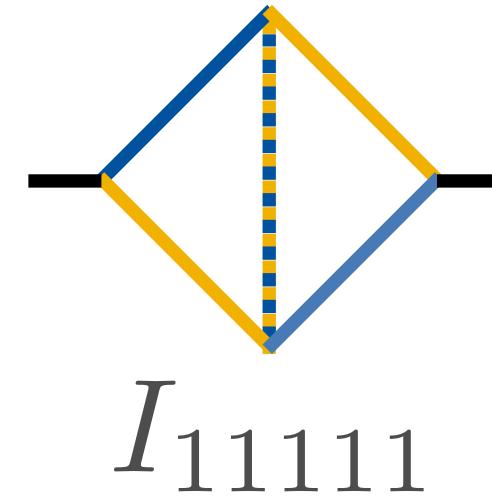
Solved with 3 masses/only one sunrise sub topology. [Adams, Bogner, Schweitzer, Weinzierl | Broedel, Duhr, Dulat, Penante, Tancredi]

THE BASIS OF MASTER INTEGRALS

The kite integral family has **30** master integrals (MIs).

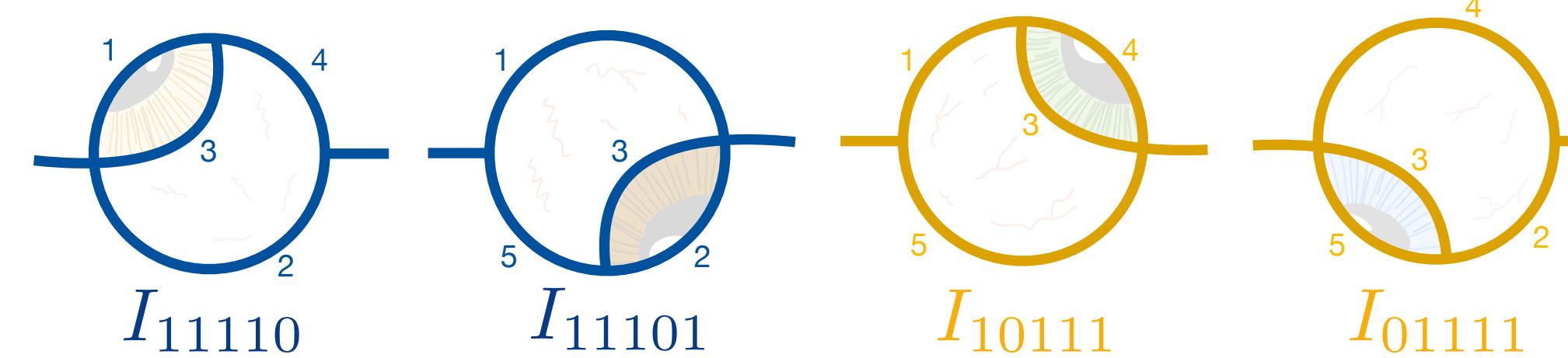
Two elliptic curves (1 MI)

The top sector:

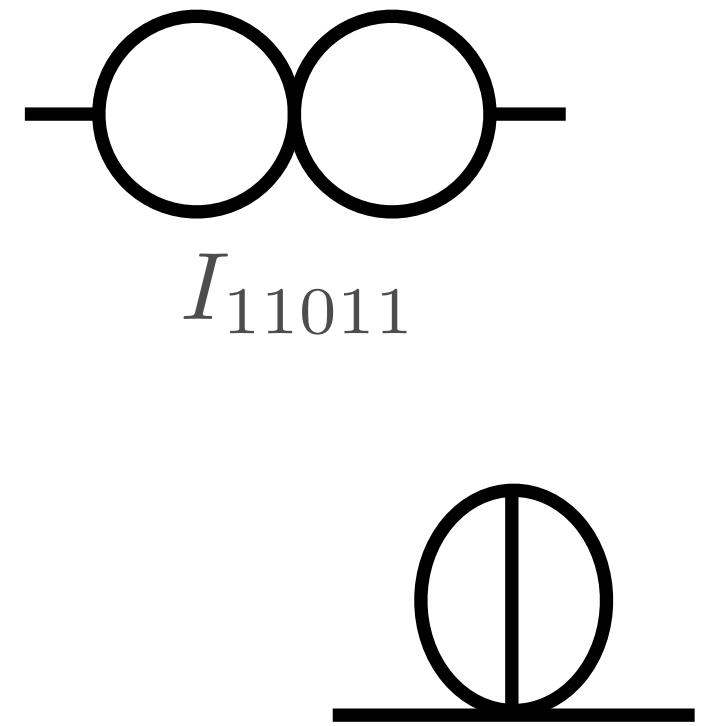


One elliptic curve (12 MI)

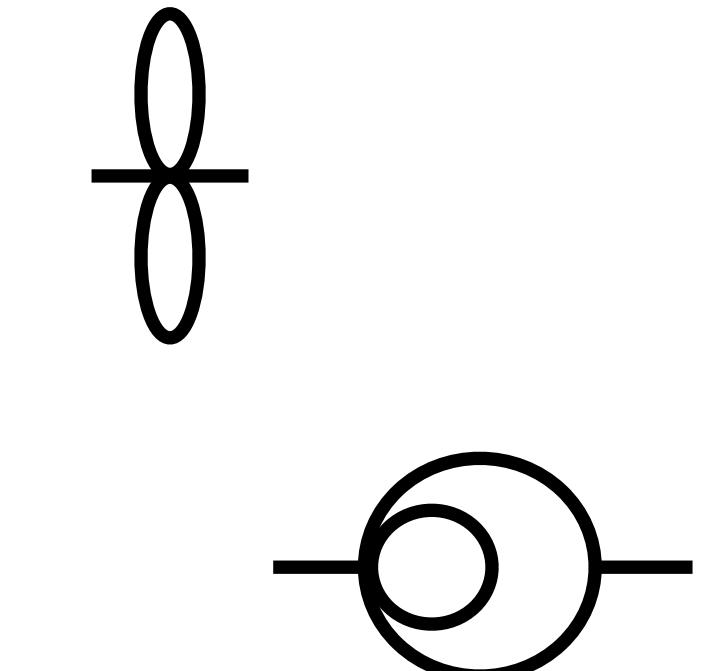
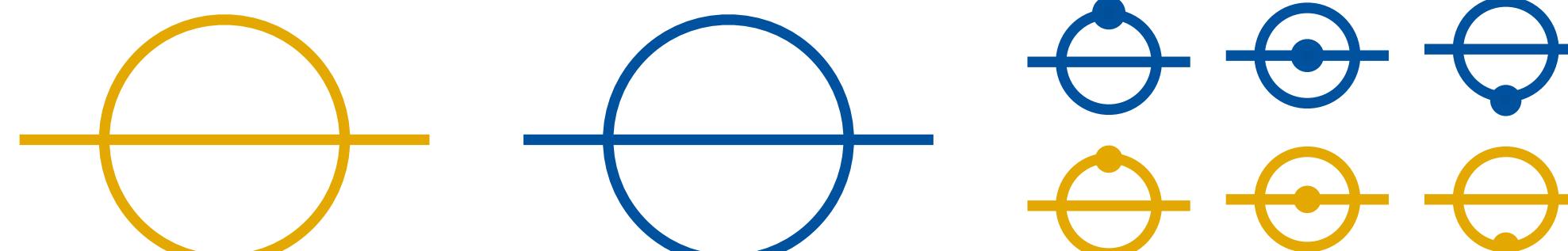
Four eyeball sub-topologies:



Not elliptic (17 MI)



The two sunrises:



METHOD OF DIFFERENTIAL EQUATIONS

We compute the kite integral family analytically with *differential equations*.

- Set up a **differential equation** w.r.t the external (kinematic) parameters

$$d\mathbf{I}(\mathbf{X}) = A(\mathbf{X}, \varepsilon)\mathbf{I}(\mathbf{X}) \quad \text{with} \quad d = \sum dX_i \partial_{X_i} \quad \text{where} \quad X_0 = \frac{p^2}{m_3^2} \quad \text{and} \quad X_i = \frac{m_i^2}{m_3^2} \quad \text{for } i \in \{1, 2, 4, 5\}$$

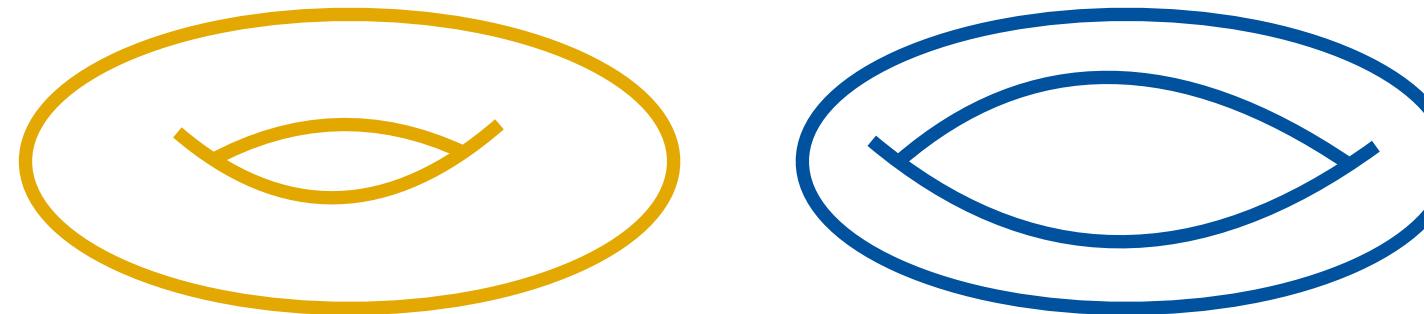
- Find an ε -form differential equation & solve in terms of **iterated integrals**. [Henn]

$$\begin{array}{c} \curvearrowleft \\ d\mathbf{J}(\mathbf{X}) = \varepsilon B(\mathbf{X})\mathbf{J}(\mathbf{X}) \end{array}$$

$$\mathbf{J}(\mathbf{X}) = \mathbb{P}\exp \left(\varepsilon \int_{\gamma} B \right) \cdot \mathbf{J}(\text{some point } \mathbf{X}^0) = \left(1 + \varepsilon \int_{\gamma} B + \varepsilon^2 \int_{\gamma} B \int_{\gamma} B + \dots \right) \cdot \mathbf{J}(\mathbf{X}^0)$$

See talks by Lorenzo Tancredi, Samuel Abreu

1. Setup: Parametrization of the kinematic space on the two tori



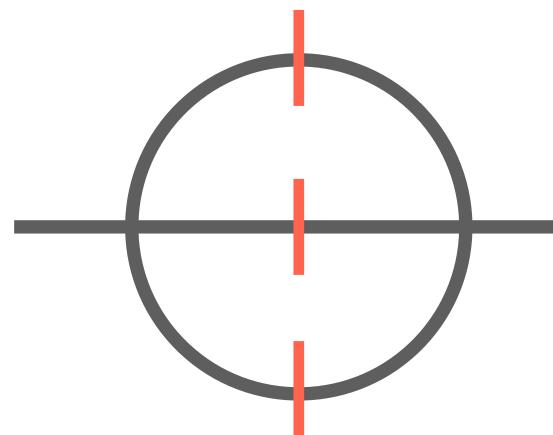
2. Transformation: Finding an ε -form differential equation (on the tori)

$$d\mathbf{J}(\underline{X}) = \varepsilon B(\underline{X})\mathbf{J}(\underline{X})$$

3. Solution: The singularity structure and iterated integrals on the tori

$$I_\gamma(\omega_1, \dots, \omega_k; \lambda) = \int_0^\lambda d\lambda_1 f_1(\lambda_1) \int_0^{\lambda_1} d\lambda_2 f_2(\lambda_2) \cdots \int_0^{\lambda_{k-1}} d\lambda_k f_k(\lambda_k) \text{ with } f_j(\lambda) d\lambda = \gamma^* \omega_j$$

THE SUNRISE ELLIPTIC CURVE

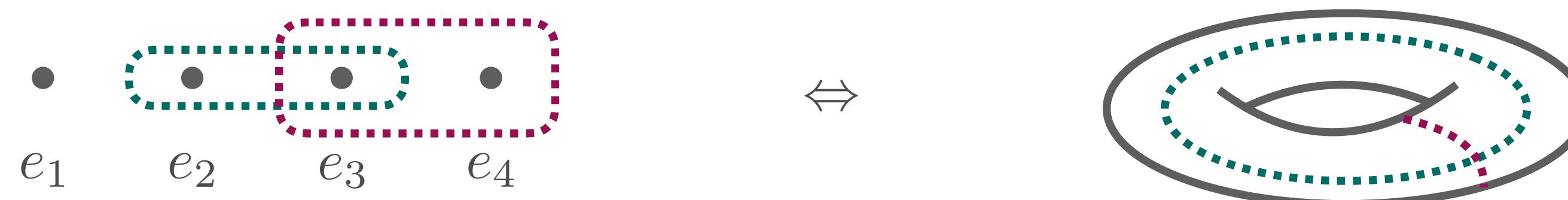

$$\sim \int_C \frac{dx}{\sqrt{(x - e_1)(x - e_2)(x - e_3)(x - e_4)}}$$

Rational functions in the kinematics

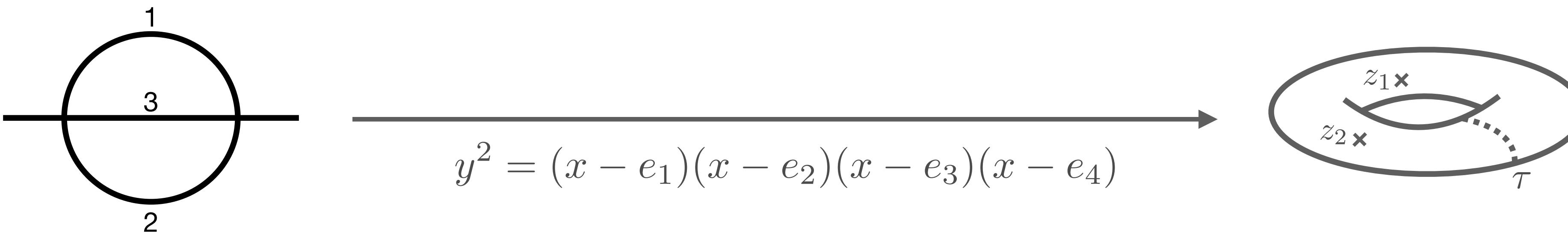
The diagram shows a circle with a horizontal axis. Three vertical red lines intersect the circle at its top, bottom, and left. The leftmost vertical line is labeled with a red bracket above and below it.

The **massive sunrise** defines an **elliptic curve** $y^2 = (x - e_1)(x - e_2)(x - e_3)(x - e_4)$ isomorphic to a **torus**.

[Laporta, Remiddi;04] [Bloch, Vanhove,13] [Bogner, Weinzierl, Müller-Stach;19] ...



SUNRISE PARAMETERS ON THE TORUS



PERIODS: $\psi_1 = 2 \int_{e_2}^{e_3} \frac{dx}{y} \sim K(k^2)$ and $\psi_2 = 2 \int_{e_4}^{e_3} \frac{dx}{y} \sim K(1 - k^2)$ with $K(k^2) = \int_0^1 \frac{dt}{\sqrt{(1-t^2)(1-k^2t^2)}}$

Ratios of polynomials in the kinematic parameters

$\rightarrow \boxed{\tau = \frac{\psi_2}{\psi_1}}$

PUNCTURES VIA ABEL'S MAP: Point on the elliptic curve \longleftrightarrow point on the torus: $(x, y) \mapsto z^\pm = \pm \frac{1}{\psi_1} \int_{e_1}^x \frac{dt}{y(t)}$

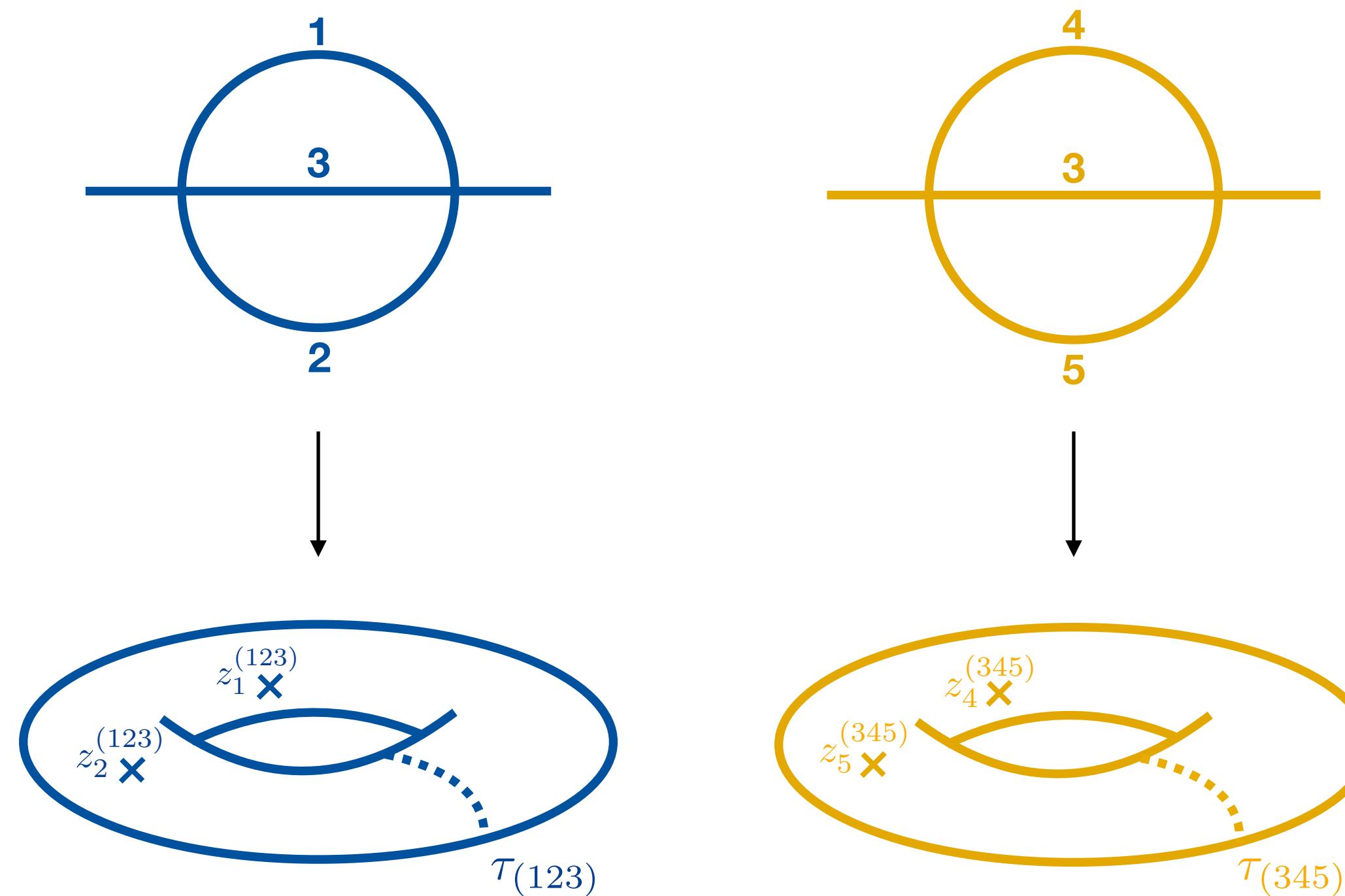
Ratios of polynomials in the kinematic parameters

$\rightarrow \boxed{z_i \sim \frac{F(\sqrt{u_i}, k^2)}{2K(k^2)}}$

[Bogner, Weinzierl, Müller-Stach;19]

with $F(\sqrt{u}, k^2) = \int_0^{\sqrt{u}} \frac{dt}{\sqrt{(1-t^2)(1-k^2t^2)}}$

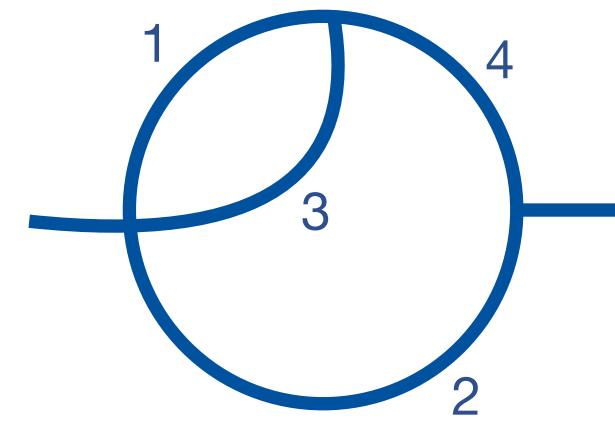
SUNRISE PARAMETERS ON THE TORI



The sunrises can be parametrized on the two tori by
 $\{\tau_{(123)}, z_1^{(123)}, z_2^{(123)}\}$ and $\{\tau_{(345)}, z_4^{(345)}, z_5^{(345)}\}$

Next: Full kinematic space of the kite on **both** tori!

THE 1234 EYEBALL ON THE 123 TORUS

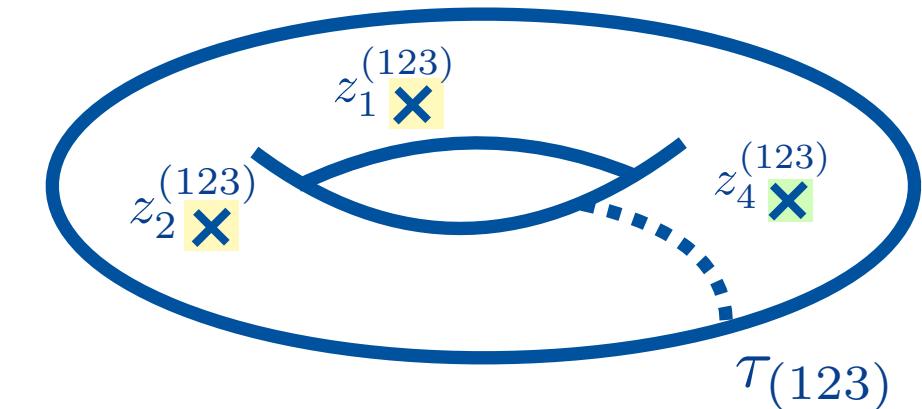


1234-eyeball

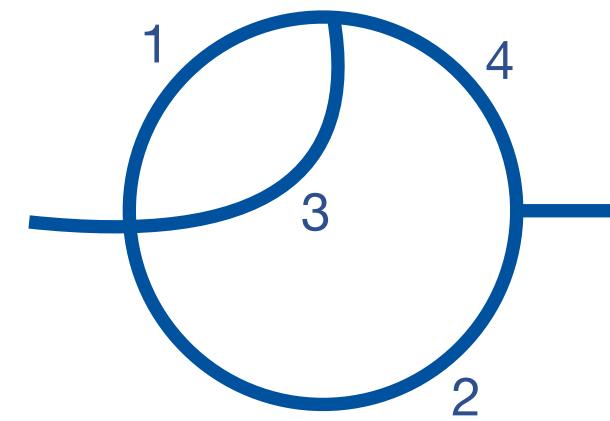
- ▶ 4 masses + p : 4 parameters
- ▶ **(123)** - torus



Period $\tau_{(123)}$
+ 3 punctures $z_1^{(123)}$, $z_2^{(123)}$ & $z_4^{(123)}$

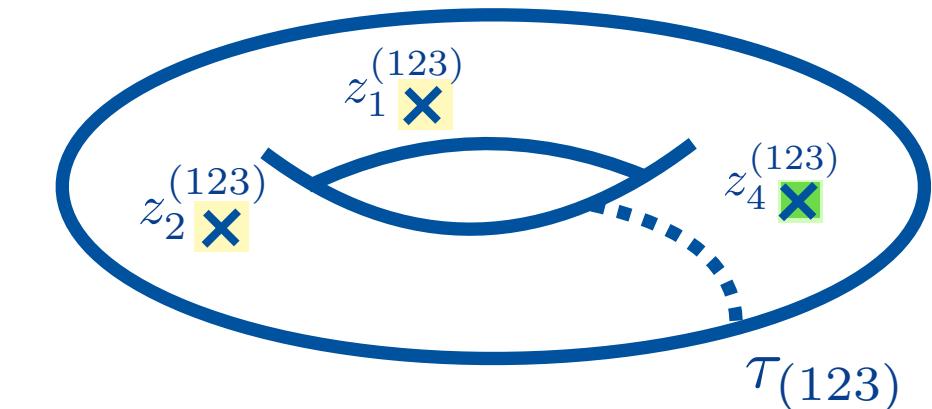


THE 1234 EYEBALL ON THE 123 TORUS



- 4 masses + p : 4 parameters
- (123) - torus

Period $\tau_{(123)}$
+ 3 punctures $z_1^{(123)}$, $z_2^{(123)}$ & $z_4^{(123)}$



We can find this **new puncture** by integrating over the maximal cut in two dimensions:

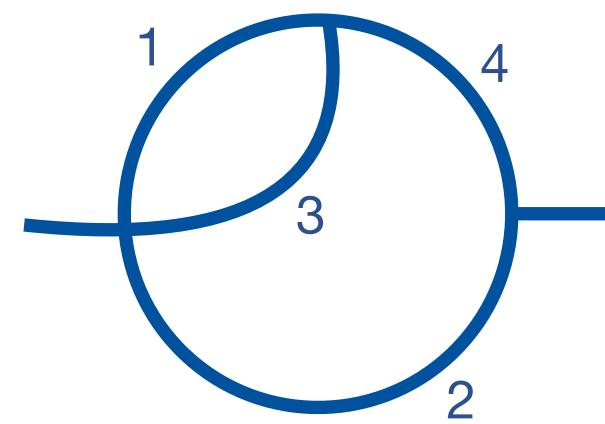
$$\int \frac{dX_4}{\sqrt{\lambda(1, X_1, X_4)\lambda(X_0, X_2, X_4)}} = \frac{1}{2} \psi_1^{(123)} \left(\frac{F(u_4, k_2)}{K(k_2)} - 1 \right) \text{ with } u_4^{(123)} = \frac{(\sqrt{X_0} + \sqrt{X_2})^2 - (\sqrt{X_1} - 1)^2}{4\sqrt{X_1}} \frac{(1 + \sqrt{X_1})^2 - X_4}{(\sqrt{X_0} + \sqrt{X_2})^2 - X_4}$$

(1234) - Eyeball MC @ 2d

$\zeta_4^{(123)}$

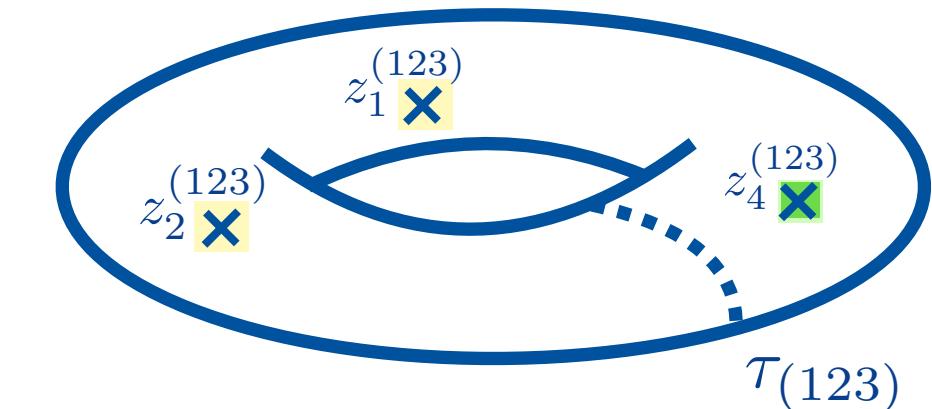
Källen function $\lambda(a, b, c) = a^3 + b^3 + c^3 + 2ab + 2ac + 2bc$

THE 1234 EYEBALL ON THE 123 TORUS



- 4 masses + p : 4 parameters
- (123) - torus

Period $\tau_{(123)}$
+ 3 punctures $z_1^{(123)}$, $z_2^{(123)}$ & $z_4^{(123)}$



We can find this **new puncture** by integrating over the maximal cut in two dimensions:

$$\int \frac{dX_4}{\sqrt{\lambda(1, X_1, X_4)\lambda(X_0, X_2, X_4)}} = \frac{1}{2} \psi_1^{(123)} \left(\frac{F(u_4, k_2)}{K(k_2)} - 1 \right) \quad \text{with} \quad u_4^{(123)} = \frac{(\sqrt{X_0} + \sqrt{X_2})^2 - (\sqrt{X_1} - 1)^2}{4\sqrt{X_1}} \frac{(1 + \sqrt{X_1})^2 - X_4}{(\sqrt{X_0} + \sqrt{X_2})^2 - X_4}$$

(1234) - Eyeball MC @ 2d

$\zeta_4^{(123)}$

Källen function $\lambda(a, b, c) = a^3 + b^3 + c^3 + 2ab + 2ac + 2bc$

We can also find the **sunrise punctures** from the maximal cut via limits:

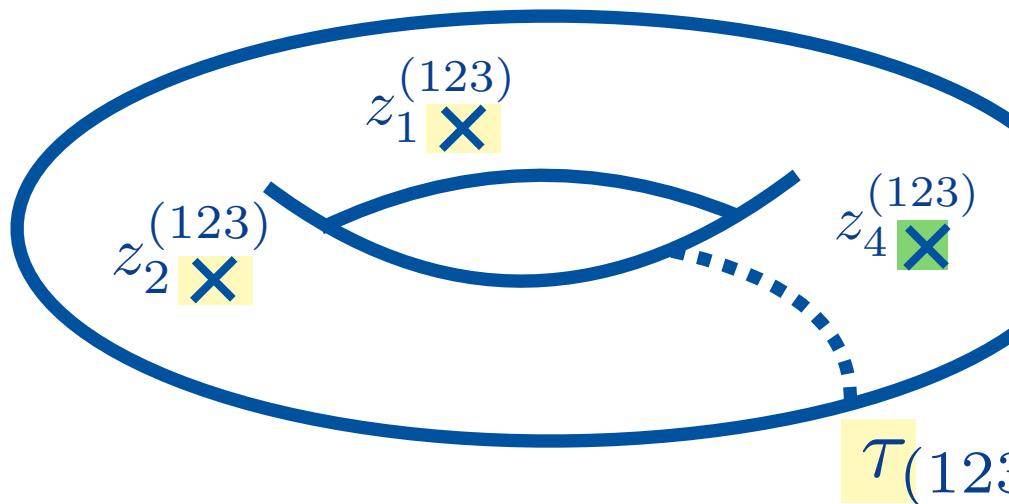
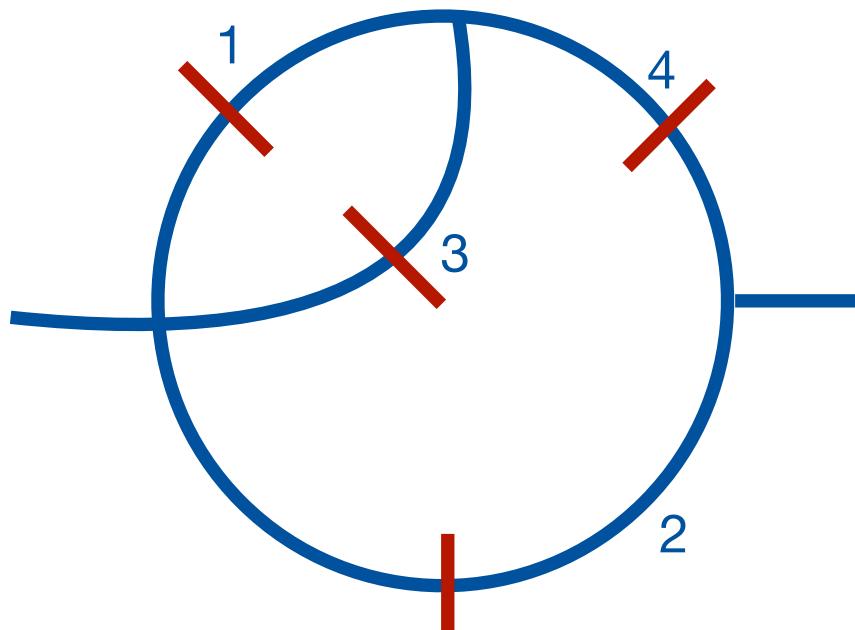
$$z_2^{(123)} \text{ from } z_4^{(123)} \text{ by } u_2^{(123)} = u_4^{(123)}|_{m_4^2 \rightarrow \infty}$$

$$z_1^{(123)} \text{ from } z_2^{(123)} \text{ by } u_1^{(123)} = u_2^{(123)}|_{m_1^2 \leftrightarrow m_2^2}$$

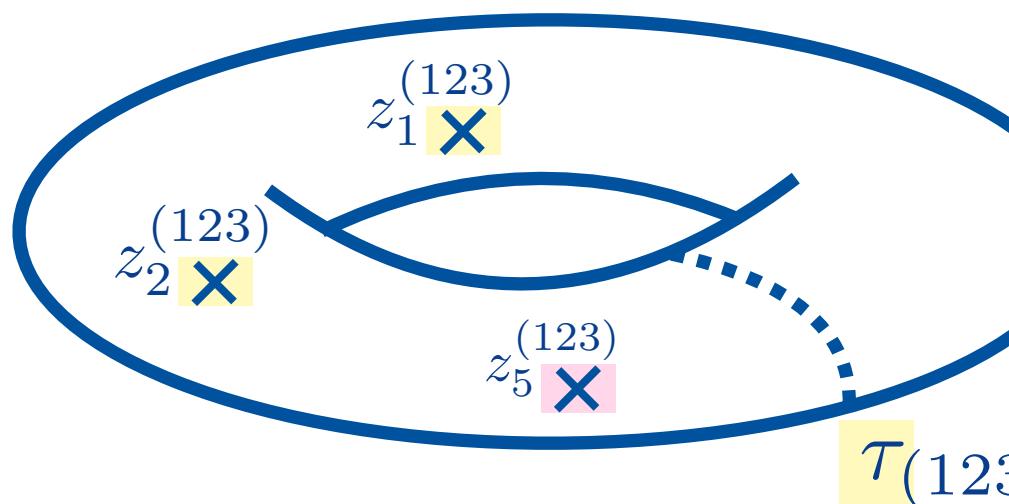
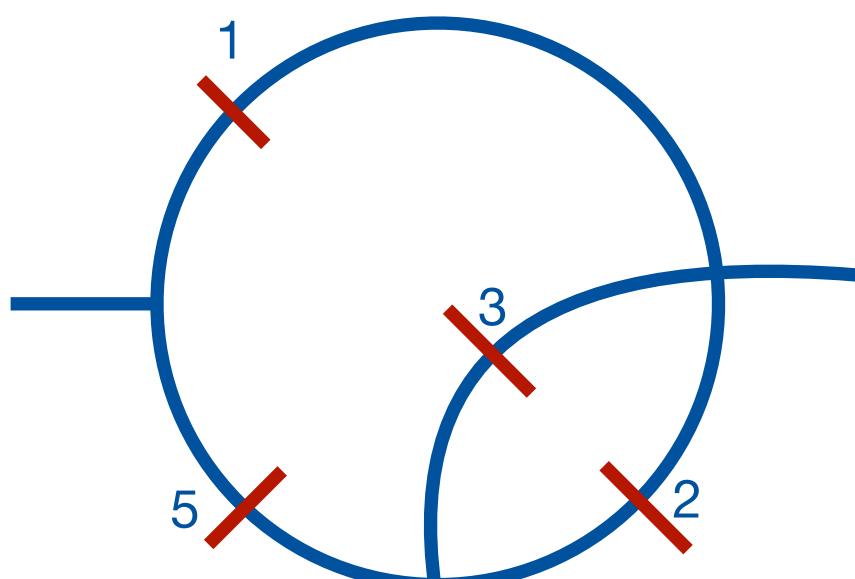
All parameters for the 1234 eyeball from a simple integral over its maximal cut in 2D.

THE KITE ON THE 123 TORUS

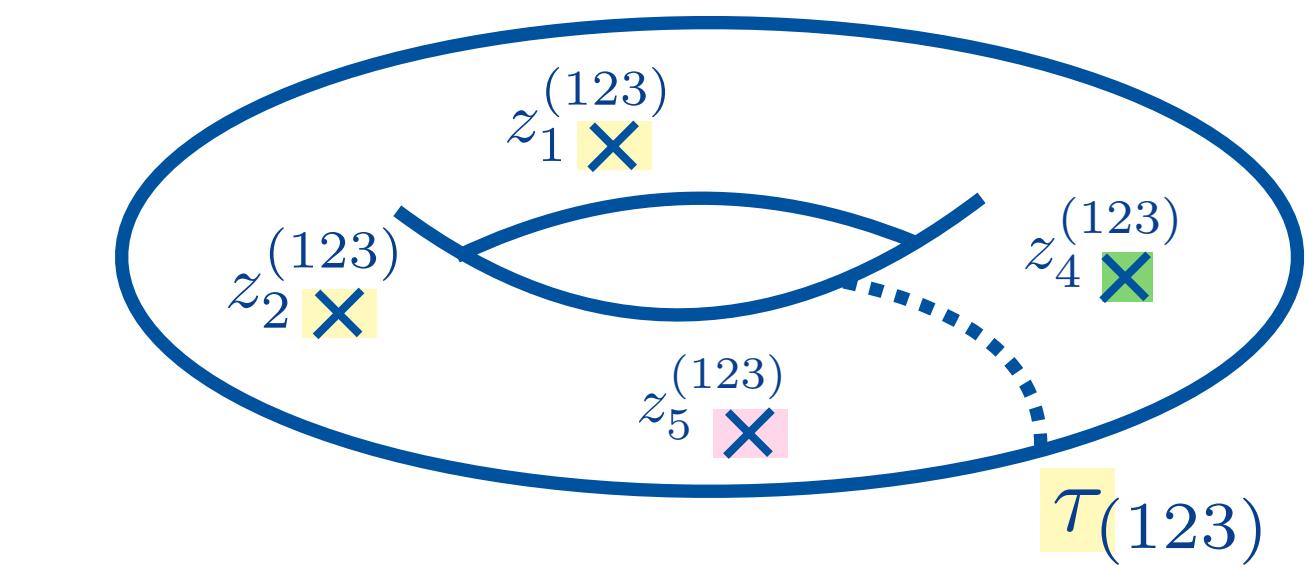
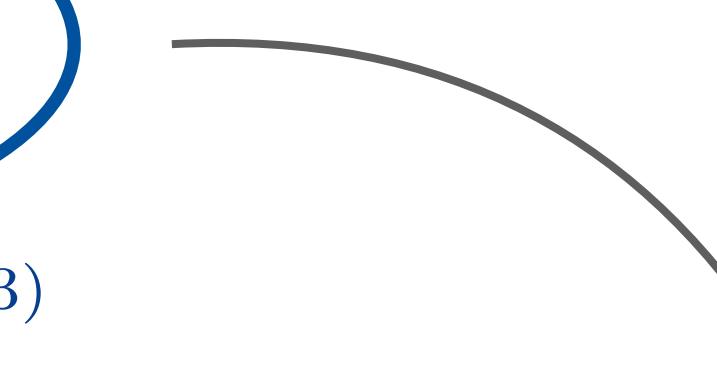
We can find *all kite punctures* on the **123-torus** from the *eyeball maximal cuts*.



$$\{ \tau_{(123)}, z_1^{(123)}, z_2^{(123)}, z_4^{(123)} \}$$



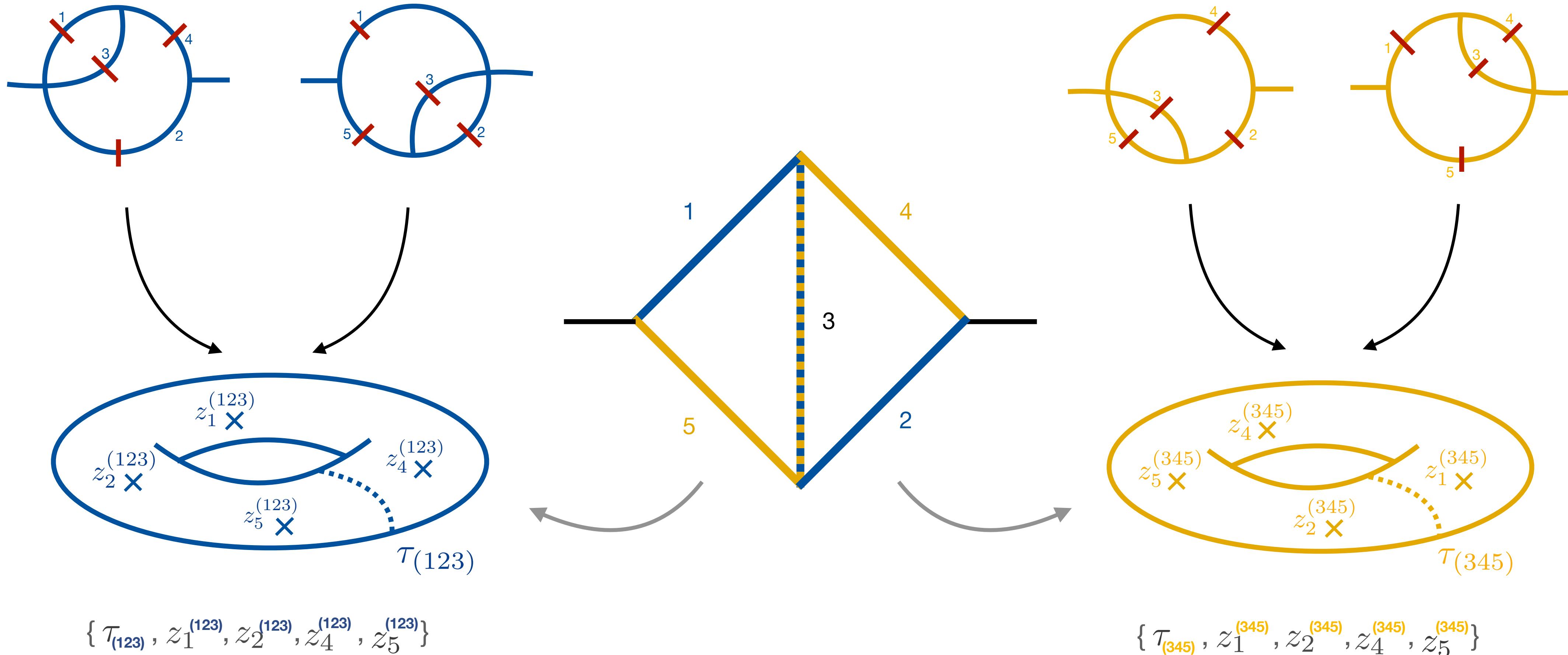
$$\{ \tau_{(123)}, z_1^{(123)}, z_2^{(123)}, z_5^{(123)} \}$$



$$\{ \tau_{(123)}, z_1^{(123)}, z_2^{(123)}, z_4^{(123)}, z_5^{(123)} \}$$



THE KITE ON THE TWO TORI



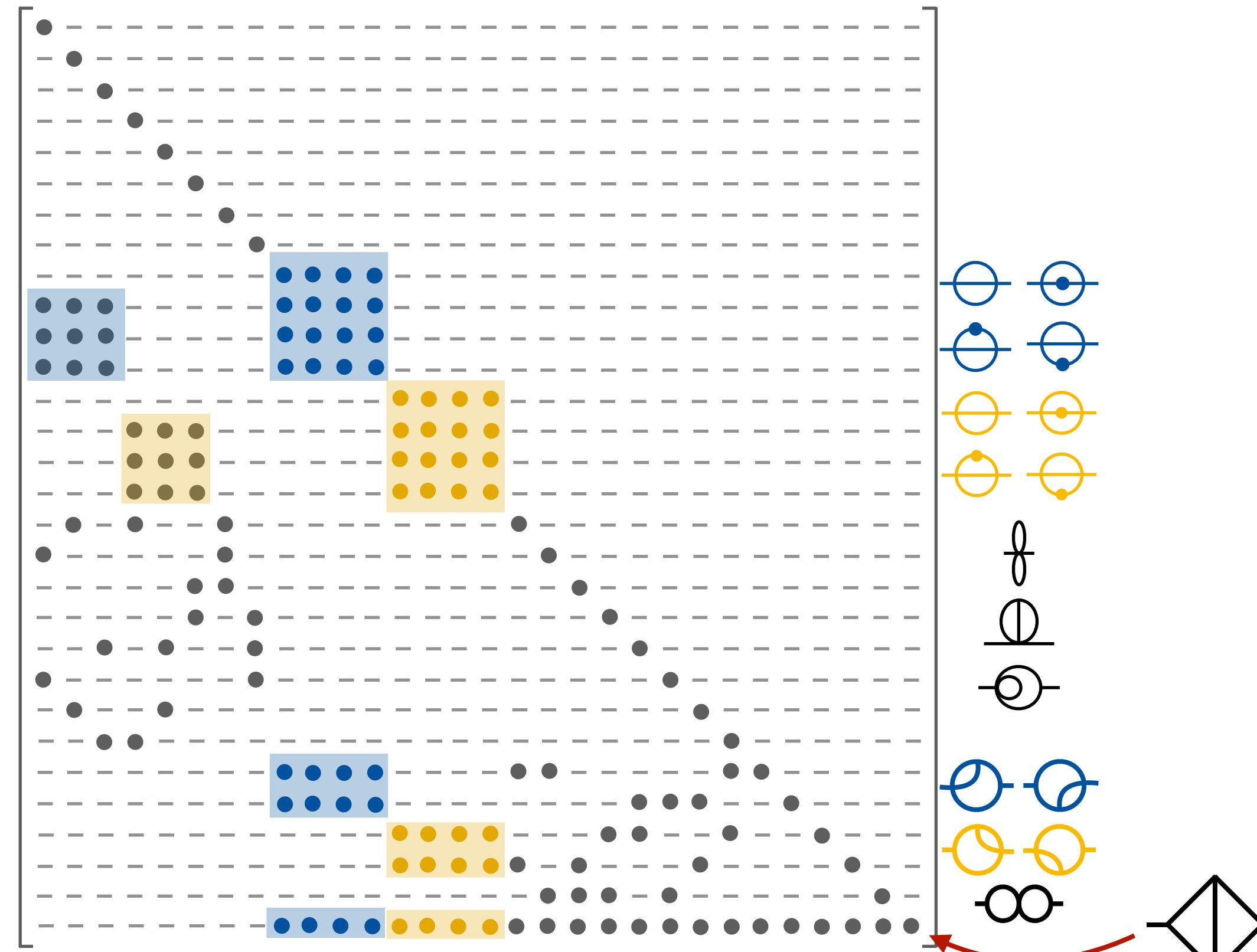
All parameters for the full kite on both tori from integrals over eyeball maximal cuts in 2D

1. Setup: Parametrization of the kinematic space on the two tori

2. Transformation: Finding an ε -form differential equation (on the tori)

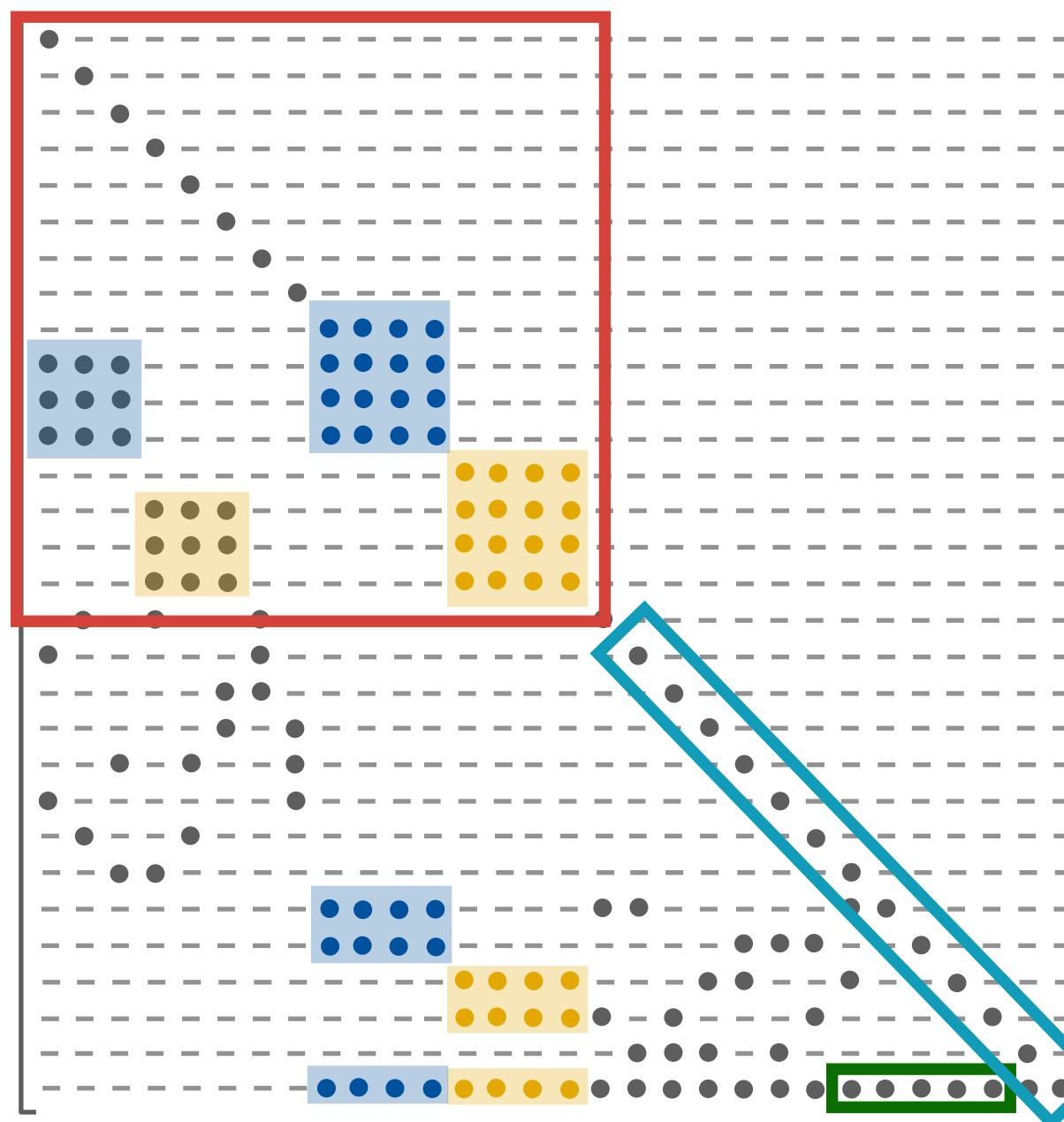
Initial: $d\mathbf{I}(\mathbf{X}) = \mathbf{A}(\mathbf{X}, \varepsilon)\mathbf{I}(\mathbf{X})$ → Goal: $\mathbf{J} = \mathbf{U}\mathbf{I}$ with $d\mathbf{J} = \varepsilon\mathbf{B}(\mathbf{X})\mathbf{J}$ & $\varepsilon\mathbf{B} = d\mathbf{U}\mathbf{U}^{-1} + \mathbf{U}\mathbf{A}\mathbf{U}^{-1}$

$$\mathbf{A}(\mathbf{X}, \varepsilon) =$$



3. Solution: The singularity structure and iterated integrals on the tori

TOWARDS ε -FORM: STEP 0-2



Step 0:

Sunrise sectors in ε -form [Bogner, Müller-Stach, Weinzierl;19]

Introduces $\partial_0 \psi_1^{(ijk)}$ and $\psi_1^{(ijk)}$ with $(ijk) \in \{ (123), (345) \}$

Step 1:

Diagonale in ε -form
(Leading singularities / Division by maximal cuts)

Step 2:

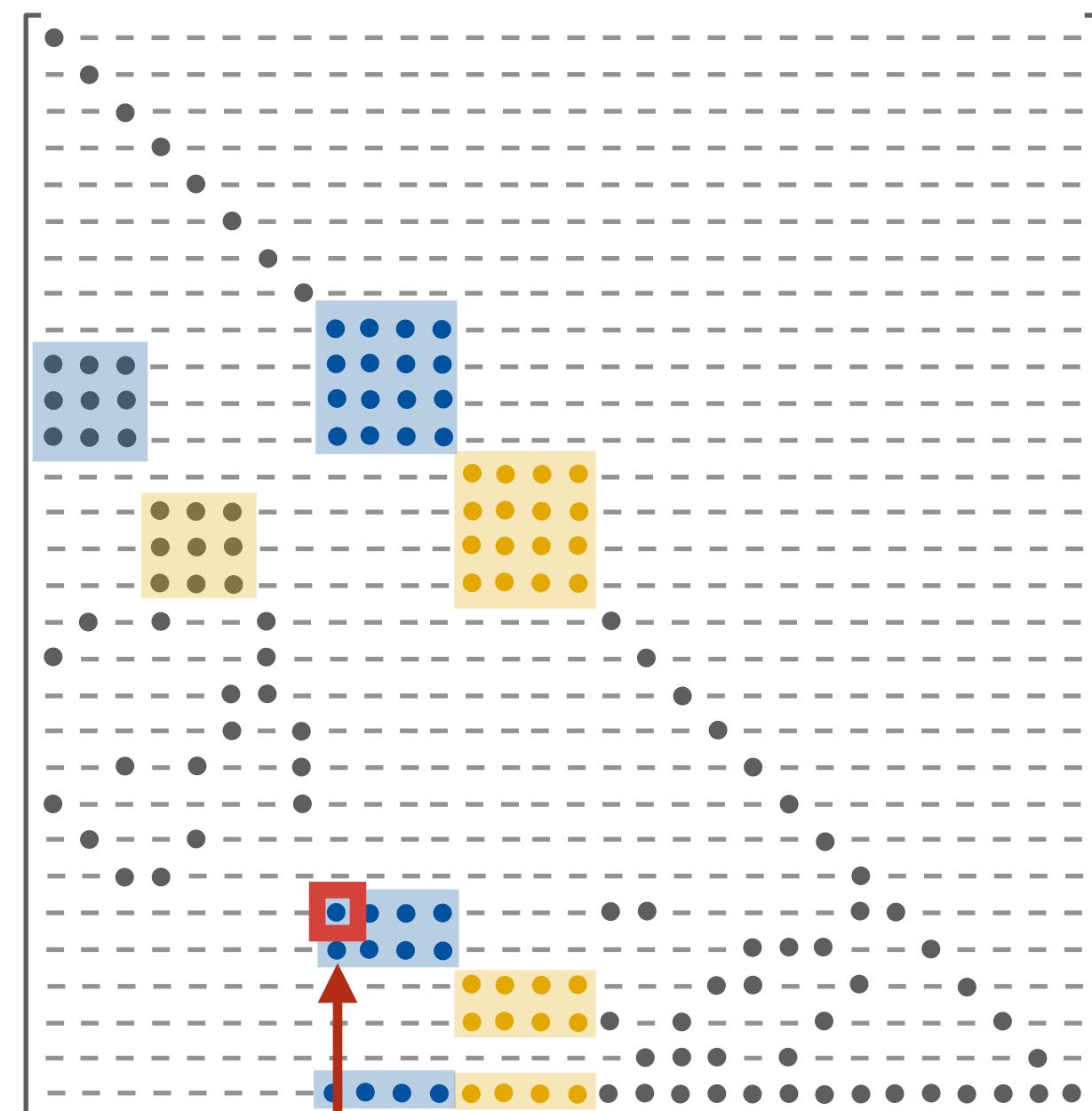
Remove the remaining non-elliptic ε^0 -terms.

New differential equation:

$$d\mathbf{J}_2(\mathbf{X}) = B_2(\varepsilon, \mathbf{X})\mathbf{J}_2(\mathbf{X})$$

TOWARDS ε -FORM: STEP 3

Remove the ε^0 terms in the $(\text{---}, \text{---})$ sector via \mathbf{U}_3 .



(25/9) or $(\text{---}, \text{---})$ - entry

Example: $(\text{---}, \text{---})$ - Entry

Make an ansatz for \mathbf{U}_3 & require: $(d\mathbf{U}_3 \mathbf{U}_3^{-1} + \mathbf{U}_3 \mathbf{B}_2 \mathbf{U}_3^{-1})_{25,9} \sim \varepsilon$

$$(U_3)_{25,9} = - \int_0^{X_4} dX'_4 (B_2)_{25,9} |_{\varepsilon \rightarrow 0}$$

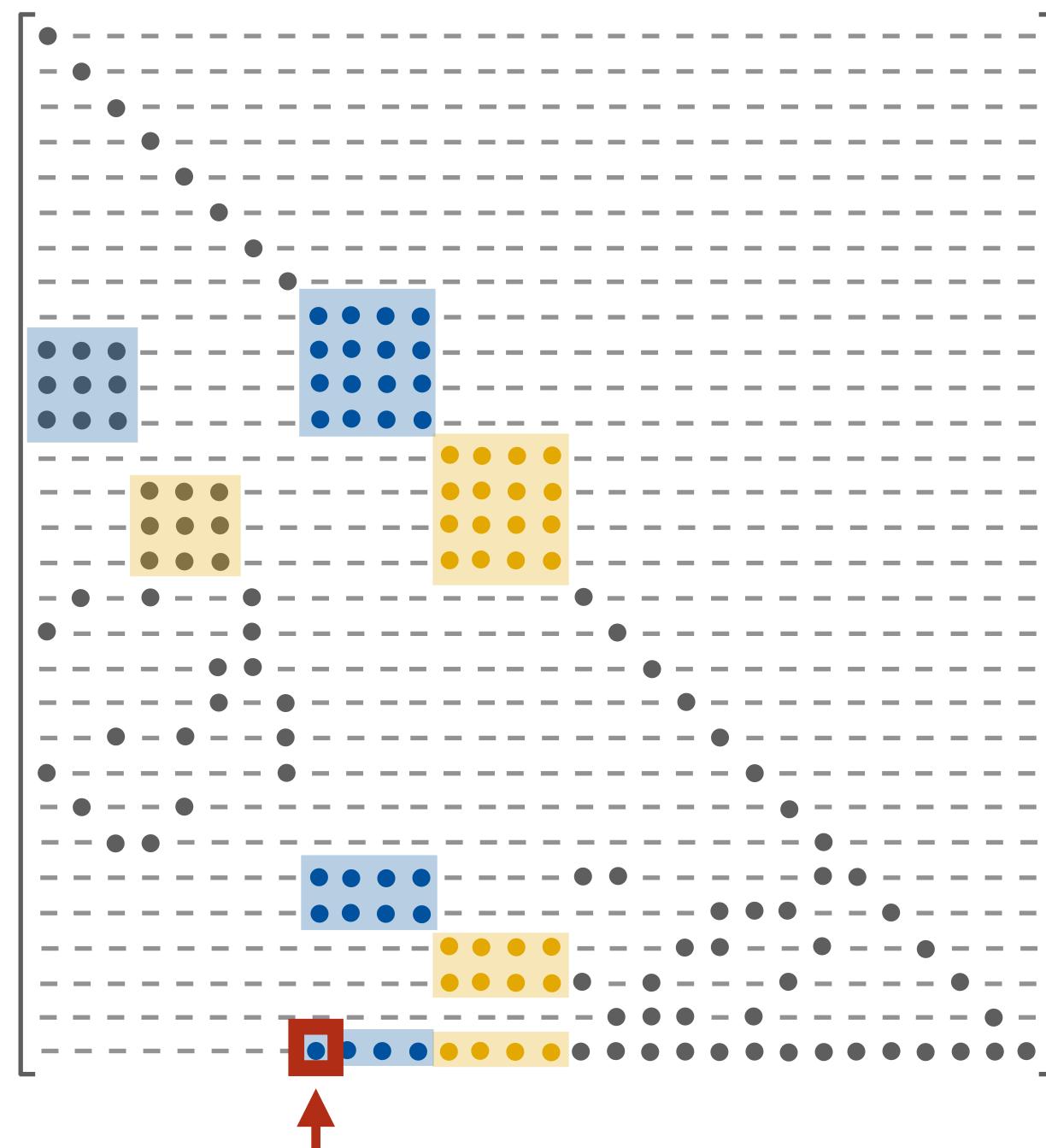
contains puncture:

$$\frac{F(u_4, k_2)}{K(k_2)}$$

All punctures for the kite on the two tori also appear naturally in the ε -form diff. equation.

TOWARDS ε -FORM: STEP 4

Remove the ε^0 - terms in the (\diamondsuit, \ominus) sector via \mathbf{U}_4 .



(30/9) or (\diamondsuit, \ominus) - entry

Example: (\diamondsuit, \ominus) - entry

Ansatz for \mathbf{U}_4 with non-trivial entry v & require ε -form after transformation

$$\Rightarrow -\tilde{B} = dv \quad \text{with } \tilde{B} = \sigma(X_i, dX_i)\psi_1 + \rho(X_i, dX_i)\partial_0\psi_1$$

Entry of the deq B_2 Entry of \mathbf{U}_4

Modular transformation:

$$(c\tau + d) \underbrace{\left(dv + \tilde{B} \right)}_0 + c \underbrace{\left(v d\tau + \rho \psi_1 \partial_0 \tau \right)}_{\dots} = 0$$

$$\Rightarrow v = -\psi_1 \partial_0 \tau \sum \rho|_{dX_j} \frac{\partial X_j}{\partial \tau}$$

Compute from the inverse of the Jacobian

→ Need all parameters (i.e. punctures) on the torus

Work on the tori to find the transformation but this requires full parametrization/all punctures.

1. Setup: Parametrization of the kinematic space on the two tori

2. Transformation: Finding an ε -form differential equation (on the tori)

$$d\mathbf{J} = \varepsilon B(\underline{X})\mathbf{J}$$

$$\mathbf{J}(\underline{X}) = \mathbb{P} \exp \left(\varepsilon \int_{\gamma} B \right) \cdot \mathbf{J} \left(\text{some point } \underline{X}^0 \right) = \left(1 + \epsilon \int_{\gamma} B + \varepsilon^2 \int_{\gamma} B \int_{\gamma} B + \dots \right) \mathbf{J} \left(\underline{X}^0 \right)$$

3. Solution: The singularity structure and iterated integrals on the tori

$$I_{\gamma}(\omega_1, \dots, \omega_k; \lambda) = \int_0^{\lambda} d\lambda_1 f_1(\lambda_1) \int_0^{\lambda_1} d\lambda_2 f_2(\lambda_2) \cdots \int_0^{\lambda_{k-1}} d\lambda_k f_k(\lambda_k) \text{ with } f_j(\lambda) d\lambda = \gamma^* \omega_j$$

g-KERNELS AND EMPLS

Formal solution for the kite: $\mathbf{J}(\underline{z}, \underline{\tau}) = \left(1 + \varepsilon \int_{\gamma} B + \varepsilon^2 \int_{\gamma} B \int_{\gamma} B + \dots \right) \mathbf{J}(\underline{z}^0, \underline{\tau}^0)$

The natural integration kernels for iterated integrals on a torus are the **g-kernels** and we use their combinations to **Kronecker forms**

$$\omega_k^{\text{Kronecker}}(z, \tau) = (2\pi)^{2-k} \left(g^{(k-1)}(z, \tau) dz + (k-1)g^{(k)}(z, \tau) \frac{d\tau}{2\pi i} \right)$$

↗ g-kernels: coefficients of the Kronecker-Eisenstein series

Iterated integrals over Kronecker forms along z are **elliptic multiple polylogarithms**:
[Brown, Levin | Brödel, Duhr, Dulat, Penante, Tancredi | Brödel, Matthes, Schlotterer]

$$\tilde{\Gamma} \left(\begin{array}{ccc} n_1 & \dots & n_k \\ w_1 & \dots & w_k \end{array}; z \right) = \int_0^z dz_1 g^{(n_1)}(z_1 - w_1) \tilde{\Gamma} \left(\begin{array}{ccc} n_2 & \dots & n_k \\ w_2 & \dots & w_k \end{array}; z \right)$$

Reorganize the differential equation B in terms of $\omega_k^{\text{Kronecker}}$ & modular forms $\eta_k(\tau)$.

THE DEQ IN KRONECKER-FORMS

Entry by entry in the differential equation:

- Determine, which Kronecker forms appear.

Decide on torus (123) or (345)

$$\omega_k \left(\sum_{n=1}^5 c_n z_n^{(ijk)}, c \cdot \tau^{(ijk)} \right)$$

$\mathcal{L}_i(z)$

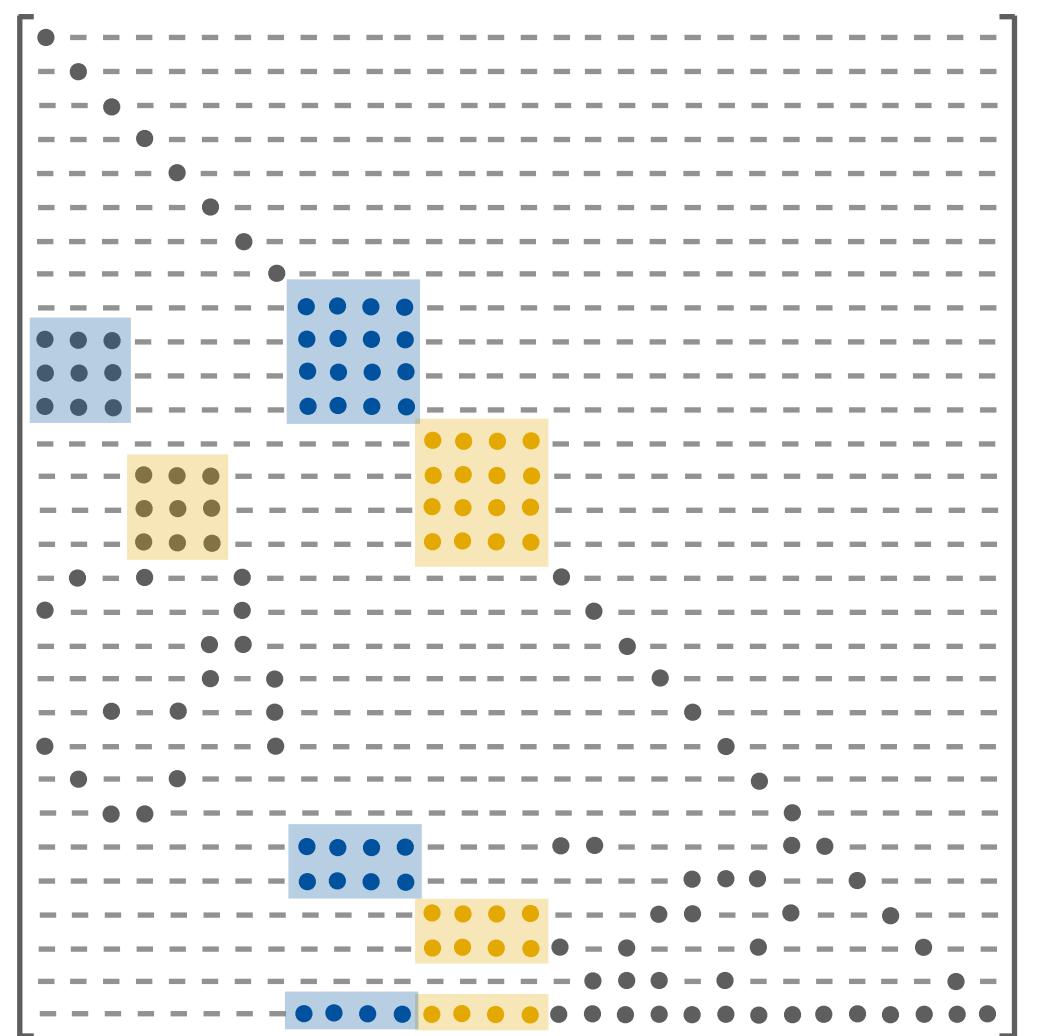
Modular behavior:

ω_k is a quasi-modular form of weight k-2

Integer (only $c=1,2$ for the kite)

Find from q-expansion ($q = e^{i\pi\tau}$)
 → Singularities!

- Numerically determine the linear combination of Kronecker forms to fix the dz part
- Numerically fix the remaining $d\tau$ part with forms $\eta_2(\tau)$ & $\eta_4(\tau)$



THE DEQ IN KRONECKER-FORMS

Any diagonal entry B_{ii} is a linear combination of dlogs:

$$B_{ii} = d \log A_1 + \cdots + d \log A_m \xrightarrow{\text{q-expansion}} d \log A_j = d \log \left(A_j^{(0)} + \mathcal{O}(q) \right)$$

Any diagonal entry B_{ii} is expressible in ω_2 :

$$B_{ii} = \sum_j c_j \omega_2(\mathcal{L}_j(z), \tau) \xrightarrow{\text{q-expansion}} \omega_2(\mathcal{L}_j(z), \tau) = d \log (\sin(\pi \mathcal{L}_j(z))) + \mathcal{O}(q^2)$$

By comparing the leading order in q , we can find the appearing arguments $\mathcal{L}_i(\underline{z})$!

The zero-loci of these $\mathcal{L}_i(\underline{z})$ are singularities on the tori.

Find 17 $\mathcal{L}_i(\underline{z})$ on each of the tori.

Examples: $\frac{1}{2}(z_2 - z_4), \frac{1}{2}(z_1 + z_2 + z_4 - z_5)$

THE RESULT IN ITERATED INTEGRALS

Boundary point: We choose for the initial point: $m_i = m > 0$ and $p^2 \rightarrow 0$

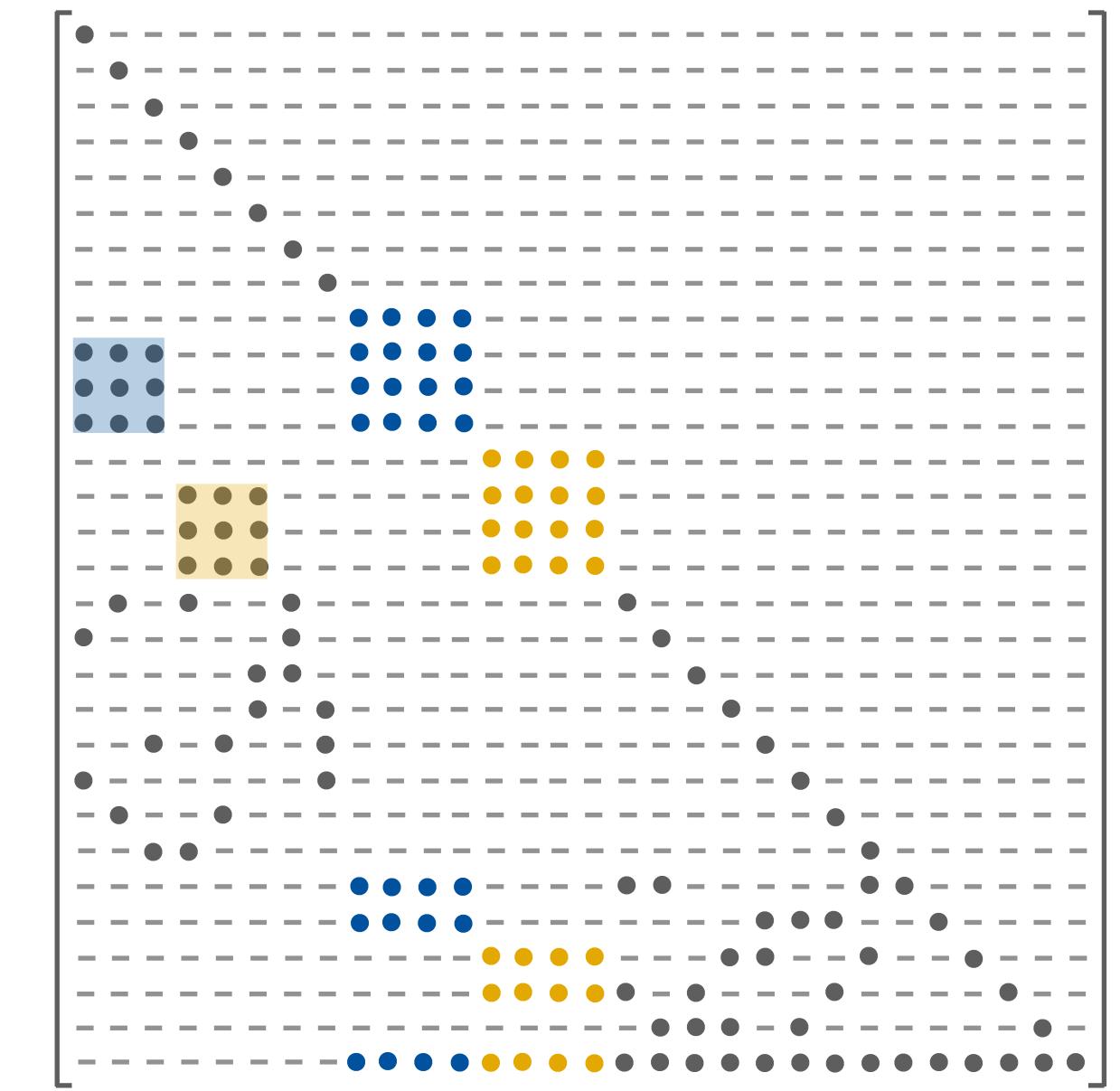
$$\mathbf{J}_0 = \varepsilon^4 \left(I_{11000} \times \vec{1}_8, \frac{\sqrt{3}I_{11100}}{2}, \vec{0}_2, -\frac{\sqrt{3}I_{11100}}{4}, \frac{\sqrt{3}I_{11100}}{2}, \vec{0}_2, -\frac{\sqrt{3}I_{11100}}{4}, i\sqrt{3}I_{11100}, \vec{0}_3, i\sqrt{3}I_{11100}, \vec{0}_9 \right)$$

Result in iterated integrals:

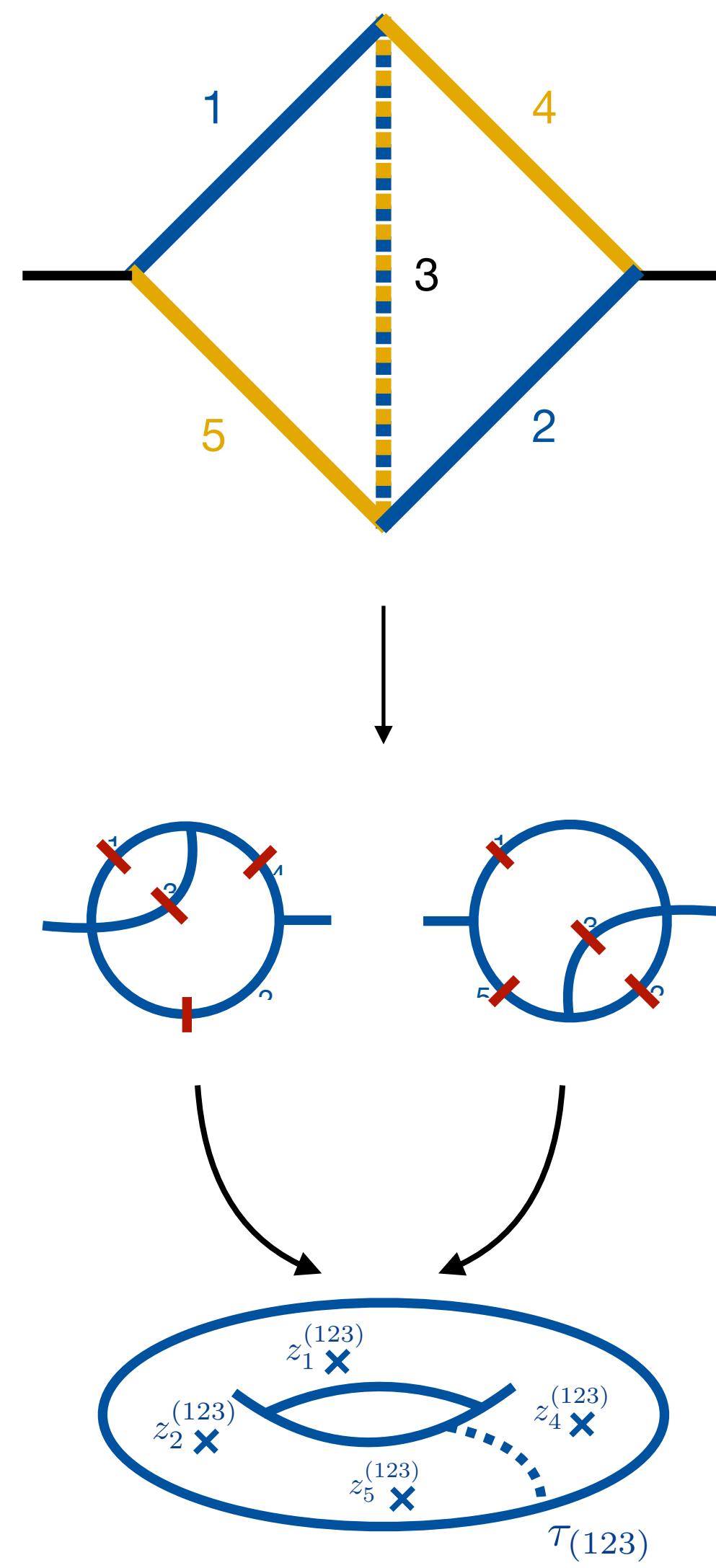
A good choice of parametrization ensures that the elliptic curves don't mix in the integrals.

$$J_i = \mathbf{J}_0 + \mathbf{J}_0 \varepsilon \left(\sum \int \omega_k^{(123)} + \sum \int \omega_k^{(345)} \right) + \mathbf{J}_0 \varepsilon^2 \left(\sum \int \omega_k^{(123)} \int \omega_k^{(123)} + \sum \int \omega_k^{(345)} \int \omega_k^{(345)} \right) + \dots$$

NO terms of the form $\int \omega_k^{(123)} \int \omega_k^{(345)}$



SUMMARY

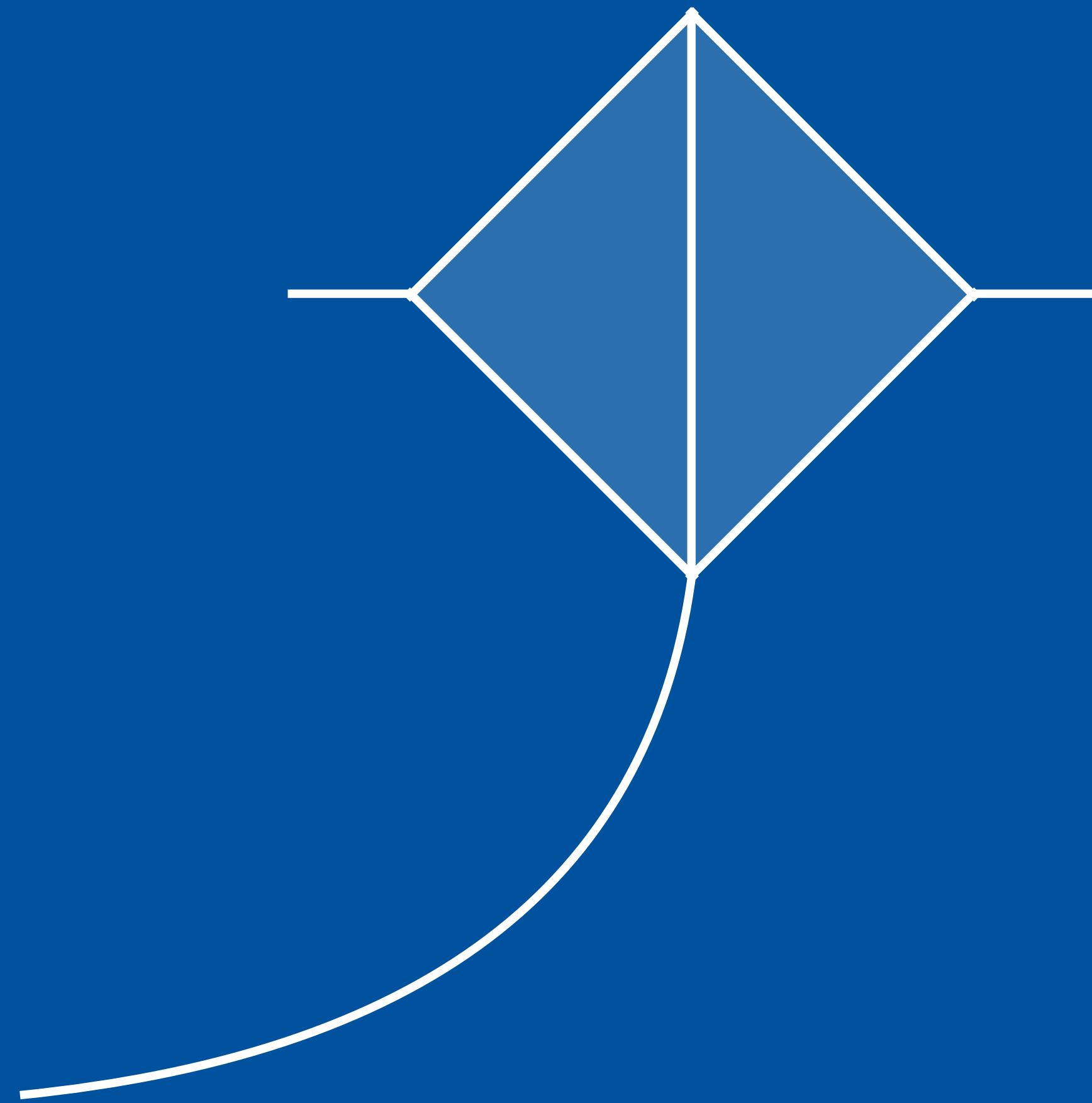


1. Parametrization of the kinematic space on the two tori:
Punctures from integrals of 2D maximal cuts of all eyeball sub topologies.
2. Finding an \mathcal{E} -form differential equation on the tori
Use the parametrization on both tori + modular transformation
3. The singularity structure and iterated integrals on the tori
Use the q-expansion to find singularites/arguments of Kronecker forms

OUTLOOK

- Other multi-scale Feynman integral families with several elliptic curves:
Can we parametrize & solve them in a similar way?
- More efficient numerics ?
- Multi-scale problems related to Calabi-Yau & hyperelliptic curves

Thank you!



Backup: Two Tori from Two Sunrises

The maximal cut of a sunrise integral with propagators α defines a quartic elliptic curve:

$$y_\alpha^2 = (x_\alpha - e_1^\alpha)(x_\alpha - e_2^\alpha)(x_\alpha - e_3^\alpha)(x_\alpha - e_4^\alpha)$$

Roots of the sunrises' elliptic curves:

$$\{e_i^{(123)}\} = \{-(\sqrt{X_1} + \sqrt{X_2})^2, -(1 + \sqrt{X_0})^2, -(1 - \sqrt{X_0})^2, -(\sqrt{X_1} - \sqrt{X_2})^2\}$$

$$\{e_i^{(345)}\} = \{-(\sqrt{X_4} + \sqrt{X_5})^2, -(1 + \sqrt{X_0})^2, -(1 - \sqrt{X_0})^2, -(\sqrt{X_4} - \sqrt{X_5})^2\}$$

Periods of the sunrises' elliptic curves:

$$\psi_1^\alpha = 2 \int_{e_2^\alpha}^{e_3^\alpha} \frac{dx_\alpha}{y_\alpha} = 2 \frac{K(k_\alpha^2)}{c_4^\alpha} \quad \text{and} \quad \psi_2^\alpha = 2 \int_{e_4^\alpha}^{e_3^\alpha} \frac{dx_\alpha}{y_\alpha} = 2i \frac{K(1 - k_\alpha^2)}{c_4^\alpha}$$

$$\text{with } c_4^\alpha = \frac{1}{2} \sqrt{(e_3^\alpha - e_1^\alpha)(e_4^\alpha - e_2^\alpha)} \quad \& \quad k_\alpha^2 = \frac{(e_3^\alpha - e_2^\alpha)(e_4^\alpha - e_1^\alpha)}{(e_3^\alpha - e_1^\alpha)(e_4^\alpha - e_1^\alpha)}$$

Backup: Two Tori from Two Sunrises

A point on the elliptic curve is mapped to a point on the torus via Abel's map:

$$(x, \pm y) \mapsto z^\pm = \pm \frac{1}{\psi_1} \int_{e_1}^x \frac{dx}{y} \bmod \Lambda_{1,\tau} = \pm \left[e^{i\arg(x-e_1) - \arg(x-e_2)} \frac{F(\sqrt{u_x}, k^2)}{2K(k^2)} + \frac{\tau}{2} \right] \text{ with } u_x = \frac{x - e_2}{x - e_1} \frac{e_1 - e_3}{e_2 - e_3}$$

Punctures for the two sunrises in the kite:

$$u_1^{(123)} = \frac{(\sqrt{X_0} + \sqrt{X_1})^2 - (\sqrt{X_2} - 1)^2}{4\sqrt{X_2}}$$

$$u_2^{(123)} = \frac{(\sqrt{X_0} + \sqrt{X_2})^2 - (\sqrt{X_1} - 1)^2}{4\sqrt{X_1}}$$

$$u_4^{(345)} = \frac{(\sqrt{X_0} + \sqrt{X_4})^2 - (\sqrt{X_5} - 1)^2}{4\sqrt{X_5}}$$

$$u_5^{(345)} = \frac{(\sqrt{X_0} + \sqrt{X_5})^2 - (\sqrt{X_4} - 1)^2}{4\sqrt{X_4}}$$

Additional punctures from the eye-balls

$$u_4^{(123)} = u_2^{(123)} \frac{(1 + \sqrt{X_1})^2 - X_4}{(\sqrt{X_0} + \sqrt{X_2})^2 - X_4}$$

$$u_5^{(123)} = u_1^{(123)} \frac{(1 + \sqrt{X_2})^2 - X_5}{(\sqrt{X_0} + \sqrt{X_1})^2 - X_5}$$

$$u_1^{(345)} = u_5^{(345)} \frac{(1 + \sqrt{X_4})^2 - X_1}{(\sqrt{X_0} + \sqrt{X_5})^2 - X_1}$$

$$u_2^{(345)} = u_4^{(345)} \frac{(1 + \sqrt{X_5})^2 - X_2}{(\sqrt{X_0} + \sqrt{X_4})^2 - X_2}$$

Backup: Modular transformations

Under a modular transformation, the periods and punctures transform in the following way:

$$z \mapsto \frac{z}{c\tau + d} , \quad \tau \mapsto \frac{a\tau + b}{c\tau + d}$$

$$\psi_1 \mapsto (c\tau + d)\psi_1 , \quad \psi_2 \mapsto (a\tau + b)\psi_2$$

$$\partial_0 \psi_1 \mapsto (c\tau + d)\partial_t \psi_1 + c\psi_1 \partial_0 \tau$$

A quasi-modular form of weight k and depth p transforms in the following way:

$$f(z, \tau) \mapsto \sum_{i=0}^p (c\tau + d)^{k+2} \left(\frac{cz}{cz + d} \right)^i f_i(z, \tau)$$

Modular behavior of B

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(C.1)

Backup: Forms on the Torus

The g-kernels

$$F(z, \eta, q) = \pi \frac{\theta'_1(0, \tau) \theta_1(\pi(z + \eta), \tau)}{\theta_1(\pi z, \tau) \theta_1(\pi \eta, \tau)} = \sum_{\alpha=0}^{\infty} \eta^{\alpha-1} g^{(\alpha)}(z, \tau)$$

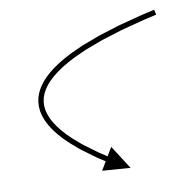
$$g^{(0)}(z, \tau) = 1$$

$$g^{(1)}(z, \tau) = \pi \cot(\pi z) + 4\pi \sin(2\pi z)q^2 + \mathcal{O}(q^4),$$

$$g^{(2)}(z, \tau) = -\frac{\pi^2}{3} + 8\pi^2 \cos(2\pi z)q^2 + \mathcal{O}(q^4),$$

$$g^{(3)}(z, \tau) = -8\pi^3 \sin(2\pi z)q^2 + \mathcal{O}(q^4),$$

$$g^{(4)}(z, \tau) = -\frac{\pi^4}{45} - \frac{16\pi^4}{3} \cos(2\pi z)q^2 + \mathcal{O}(q^4).$$



$$\omega_2(z, \tau) = d \log \frac{\theta_1(\pi z, \tau)}{\eta(\tau)} = d \log \sin(\pi z) + \mathcal{O}(q^2),$$

The η - function

$$\eta_2(\tau) = [e_2(\tau) - 2e_2(2\tau)] \frac{d\tau}{2\pi i} \quad \text{with} \quad e_2(\tau) = \frac{2\pi^2}{6} \frac{\theta_1'''(0, \tau)}{\theta_1'(0, \tau)}$$

$$\eta_4(\tau) = e_4(\tau) \frac{d\tau}{(2\pi i)^3} \quad \text{with} \quad e_4(\tau) = \frac{\pi^4}{90} (\theta_2^8(0, \tau) + \theta_3^8(0, \tau) + \theta_4^8(0, \tau))$$

Backup: More q-expansion behavior

$$d \log(X_0|_{q^2}) = d \log \left(\sin^2(\pi z_1) \sin^2(\pi z_2) \right),$$

$$d \log(X_4|_{q^0}) = d \log \frac{\sin\left(\frac{\pi}{2}(2z_1+z_2+z_4)\right) \sin\left(\frac{\pi}{2}(2z_1+z_2-z_4)\right) \sin^2(\pi z_2)}{\sin^2(\pi(z_1+z_2)) \sin\left(\frac{\pi}{2}(z_2+z_4)\right) \sin\left(\frac{\pi}{2}(z_2-z_4)\right)},$$

$$d \log(\lambda_{024}|_{q^0}) = d \log \frac{\sin^2(\pi z_1) \sin^4(\pi z_2)}{\sin^2(\pi(z_1+z_2)) \sin^2\left(\frac{\pi}{2}(z_2+z_4)\right) \sin^2\left(\frac{\pi}{2}(z_2-z_4)\right)},$$

$$d \log(\lambda_{134}|_{q^0}) = d \log \frac{\sin^2(\pi z_1) \sin^2(\pi z_2) \sin^2(\pi z_4)}{\sin^2(\pi(z_1+z_2)) \sin^2\left(\frac{\pi}{2}(z_2+z_4)\right) \sin^2\left(\frac{\pi}{2}(z_2-z_4)\right)}.$$

Backup: Initial condition detailed

$$\tau_0^{(123)} = \tau_0^{(345)} = i\infty$$

$$m_i = m > 0 \text{ and } p^2 \rightarrow 0 \iff z_1^{(123)} = z_2^{(123)} = z_4^{(345)} = z_5^{(345)} = \frac{1}{3}$$

$$z_4^{(123)} = z_5^{(123)} = z_1^{(345)} = z_2^{(345)} = \frac{1}{2} - i\infty$$



$$\mathbf{J}_0 = \varepsilon^4 \left(I_{11000} \times \vec{1}_8, \frac{\sqrt{3}I_{11100}}{2}, \vec{0}_2, -\frac{\sqrt{3}I_{11100}}{4}, \frac{\sqrt{3}I_{11100}}{2}, \vec{0}_2, -\frac{\sqrt{3}I_{11100}}{4}, i\sqrt{3}I_{11100}, \vec{0}_3, i\sqrt{3}I_{11100}, \vec{0}_9 \right)$$

- $I_{11000}(\underline{X}_0) = e^{2\gamma_{\text{EM}}\varepsilon} \Gamma^2(\varepsilon)$
- $I_{11100}(\underline{X}_0) = \frac{e^{2\gamma_{\text{EM}}\varepsilon} \Gamma(1+2\varepsilon)}{(-1)^{1+2\varepsilon} 3^{1/2+\varepsilon}} \left[\left(-e^{\frac{2i\pi}{3}}\right)^{-\varepsilon} F_\varepsilon\left(\frac{2i\pi}{3}\right) - \left(-e^{-\frac{2i\pi}{3}}\right)^{-\varepsilon} F_\varepsilon\left(-\frac{2i\pi}{3}\right) + \frac{\pi}{\varepsilon} \right]$

with $F_\varepsilon(z) = \frac{3i\Gamma^2(\varepsilon+1)}{2\varepsilon^2\Gamma(2\varepsilon+1)} {}_2F_1(-2\varepsilon, -\varepsilon, 1-\varepsilon, e^z)$

Integrating along τ with the common base point $\tau_0^{(123)} = \tau_0^{(345)} = i\infty$ and fixed z_i we obtain:

$$J_{30}^{(2)} = \sum_{j=6}^9 (-1)^{\delta_{j,6} + \delta_{j,7}} ([\Omega_{2,j,1}^{(123)}, \Omega_{2,1,1}^{(123)}] - 2[\Omega_{2,j,1}^{(123)}, \Omega_{2,1,2}^{(123)}] - [\Omega_{2,j,1}^{(123)}, \Omega_{2,5,1}^{(123)}] + 2[\Omega_{2,j,1}^{(123)}, \Omega_{2,5,2}^{(123)}])$$

$$+ \sum_{j=6}^9 (-1)^{\delta_{j,10} + \delta_{j,11}} ([\Omega_{2,j,1}^{(123)}, \Omega_{2,2,1}^{(123)}] - 2[\Omega_{2,j,1}^{(123)}, \Omega_{2,2,2}^{(123)}] - [\Omega_{2,j,1}^{(123)}, \Omega_{2,5,1}^{(123)}] + 2[\Omega_{2,j,1}^{(123)}, \Omega_{2,5,2}^{(123)}])$$

$$+ (\text{(123)} \leftrightarrow \text{(345)}) \quad \text{with} \quad \Omega_{a,b,c}^d = \omega_a(\mathcal{L}_b^d, c\tau_d) \quad \text{and} \quad [\omega_1, \omega_2] = \int_{i\infty}^{t_1} \omega_1(t_1) \int_{i\infty}^{t_2} \omega_2(t_2)$$